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Seismic input models for tuned mass damper designing

Расчетное сейсмическое воздействие для сооружения с динамическим гасителем колебаний

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Abstract. The subject of investigations is seismic input models for tuned mass damper designing. Some features of simulating design accelerograms for estimating seismic stability of a structure with a mass damper are considered. The method of accelerogram modeling, proposed by Dolgaya A.A., approved by the Building Ministry of Russian Federation and included in the corresponding Recommendations in 1996, is considered as the basic one. In accordance with this method, an accelerogram is modeled by a sum of three damped sinusoids. The sinusoid frequencies are chosen as dangerous for the structure, and the amplitudes and damping parameters are chosen so that the kinematic and energy characteristics of the model input correspond to the actual ones. The main feature of MD designing is the presence of close frequencies, and the choice of a dangerous frequency is not unambiguous. Features of choosing a dangerous frequency and the influence of various characteristics of real accelerograms on the generated synthetic accelerogram are considered.

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Аннотация. Рассматриваются особенности моделирования расчетных акселерограмм для оценки сейсмостойкости сооружения с динамическим гасителем колебаний. В качестве базового рассмотрен метод А.А.Долгой, вошедший в Рекомендации Госстроя РСФСР, утвержденные в 1996 году. В соответствии с этим методом акселерограмма моделируется набором из трех затухающих синусоид. Частоты синусоид подбираются опасными для сооружения, а амплитуды и показатели затухания выбираются так, чтобы кинематические и энергетические характеристики модельного воздействия соответствовали натурным. Основной особенностью конструкций с ДГК является наличие близких частот, и выбор опасной частоты не является однозначным. Рассматриваются особенности выбора опасной частоты и влияние различных характеристик воздействия на вид синтетической акселерограммы.

Introduction

Tuned mass dampers (MD) were proposed by H. Fram in 1911 [1, 2]. In the years that followed, many well-known specialists were engaged in optimizing the MD tuning and damping [3–5]. The summing up of studies on the MD problems is given in a well-known monograph by B.G. Korenev and L.M. Reznikov [6]. Since the end of the 70-s of the last century proposals to use the MD for seismic protection of buildings and structures have been made [7–11]. In the recent 20 years the MD began to be widely used for structure protection, i.e. for high-rises building protection against winds and earthquakes in Taipei, Shanghai and other countries [13, 14]. At present, the MD are produced by leading firms in the field of vibration protection such as Maurer Söhnes, FIP Industrial and others. Not long ago investigations on applying the MD in designing non-symmetrical buildings of complicated configuration [15, 16] as well as for non-linear systems [17] and bridges [18] are begun. In order to increase the MD efficiency for seismic protection of structures, it was proposed to use the MD of large mass with a part of the structure itself, being used in the MD [6, 7]. In particular, in [7], it was discovered that there exists the critical mass of the MD, above which the dynamic damping effect disappears, and the MD turns into Lanchester damper. The description of the MD for seismic protection of structures is included in textbooks and teaching aids, as well as in the Guidelines [20, 21]. In the presence of a large number of studies and the apparent simplicity of the problem, attempts to use the MD still bring surprises for scientists. For example, in 2016-17 the essential dependence of the MD tuning, damping and the critical mass on damping in the structure was found [12]. Foreign specialists also found the necessity of taking into account damping in the construction [23, 24]. However, analyzing systems with heterogeneous damping faced with certain difficulties. The normative version of the response spectra method (RSM) cannot be used for inhomogeneous damping. A complete version of the RSM of damped systems was proposed in [15, 25], but has not been used in designing practice yet. The main method of assessing seismic resistance of heavily damped systems remains time-history calculation using accelerograms of earthquakes. Such calculations give designers some freedom, which can result in completely different estimates of seismic resistance. One can see this sort of results in paper [19]. In the authors' opinion, the main problem here is to set seismic input.

The study aim is founding seismic input features for estimating the seismic stability of structures with the MD, in order to exclude errors and ambiguous results of such assessment.

Two approaches to generating design accelerograms have been developed in the earthquake engineering practice. These approaches are described in detail in scientific [16] and educational [8] literature. The first approach is generating design accelerograms for the building site. It can be used when reliable seismological information is available and if the authors of the design accelerograms are ready to bear financial and legal responsibility for them, which is possible when designing highly responsible structures. For mass and especially typical designing it is necessary to use the second method of generating accelerograms, i.e. generating accelerograms for the structure. In this case, the input spectral composition is chosen as dangerous for the structure, and the generated process parameters are chosen so that the characteristics of the model input correspond to the actual ones. In its turn, generating accelerograms for a structure includes 5 methods as follows:

1. Using a package of accelerograms of past earthquakes
2. Choosing a set of narrowband processes
3. Setting a single broadband process
4. Generating a process with a spectrum that coincides with the normative response spectrum
5. Generating a narrowband process dangerous for the structure

These methods are considered in detail in [17]. We only note that the use of this or that technique is always a trade-off between ensuring the danger of the design input for the structure and the similarity of the input to real accelerograms. Thus, for the oscillator, the input in the form of a rectangular sine with the natural oscillator frequency is the most dangerous. For the structure it is possible to set the input in the form of successive harmonics so that each oscillation mode of the structure passes through resonance. Such inputs are dangerous for the construction, but are not like real accelerograms at all. If deliberately dangerous input led to acceptable technical solutions, their further specification and approximation to the real ones would not be necessary. However, as a rule, this does not occur, and the task of specifying the design input is rather urgent. Below, the authors consider setting the abovementioned narrow-band process to be dangerous for the building in calculating structures with the tuned mass damper (MD).

Materials and methods of research

At the description statement of input model a multiparameter narrow-band process can be defined in various ways [18–20]. Below, the model proposed in [18] is considered, but the conclusions obtained on its basis are valid for other models of this type. In accordance with [18], the velosigram of the model input is presented as the sum of three damped sinusoids

$$\dot{y}(t) = \sum_{i=1}^3 A_i e^{-\varepsilon_i t} \cdot \sin \omega_i t \quad (1)$$

In the process under consideration frequencies ω_i are chosen as dangerous (resonant) for the structure. The amplitude A_2 is determined by the condition $\dot{y}(t) = 0$. The rest 5 parameters $A_1, A_3, \varepsilon_1, \varepsilon_2, \varepsilon_3$ are set so that the characteristics of the model process correspond to the field data. In [19] peak ground accelerations (PGA), depending on the frequency of oscillations, and Arias intensity I_A were accepted as the input characteristics. Recent studies make it possible to take into account a wider range of seismic input characteristics. The analysis of these characteristics is given in [21]. When generating the impact, the authors took into account 5 characteristics of real accelerograms.

1. Peak ground acceleration, $\ddot{y}_0^{(\max)}$, PGA.

2. Coefficient of process harmonicity κ ,

$$\kappa = \frac{\ddot{y}_0^{(\max)} \cdot y_0^{(\max)}}{(\dot{y}_0^{(\max)})^2} \quad (2)$$

where $y_0^{(\max)}$ is the maximum displacement of the base, and $\dot{y}_0^{(\max)}$ is the maximum velocity of the base.

3. Arias intensity I_A

$$I_A = \frac{\pi}{2g} \int_0^T \ddot{y}_0^2 dt. \quad (3)$$

4. Absolute cumulative velocity CAV

$$CAV = \int_0^T |\ddot{y}_0| dt \quad (4)$$

5. Seismic energy density SED

$$SED = \int_0^T \dot{y}_0^2 dt \quad (5)$$

The first two characteristics are referred to kinematic ones, and the next three are attributed to energy characteristics.

The foregoing approach is aimed at generating a dangerous design input and taking into account important features of actual impacts.

Two features of the method of input generating under consideration, which are not taken into account in [18, 19] should be noted.

First, the parameters of the input are determined approximately, parameter weighting factors are given for each parameter and the difference between the characteristics of the model and the actual input is minimized taking into account these parameters. Thus, it is possible to construct the infinite number of model processes with a given spectral composition. Secondly, in [19, 20] the first component of the process is considered as the main one. It is assumed that it accounts for minimum half of the SED value, i.e. the following condition takes place.

$$A_1^2 > A_2^2 + A_3^2 \quad (6)$$

The foregoing statement of the problem of seismic input generating is suitable for calculating structures with a rarefied spectrum in which the main part of the seismic load is provided by the first oscillation mode. Meanwhile, in design practice, one has to deal with structures having a dense spectrum. In this case, a dangerous mode is not known in advance. The simplest object of this type is the construction with the MD. The specifics of the input setting for such structures are discussed below.

Results and Discussion

Setting the seismic input to assess the effectiveness of MD. When calculating systems with the MD, it is necessary to deal with at least three characteristic frequencies. This fact is illustrated in Fig. 1, which shows the gain-frequency characteristic of an oscillator with eigen frequency k_0 and with static displacement A_{st} . For the structure without the MD the dangerous frequency is ω_0 , and for the structure with the MD there are two dangerous frequencies ω_1 and ω_2 , and the amplitudes of oscillations at these frequencies coincide. In this regard, for the example under consideration it is necessary to generate three design accelerograms: the basic one, for calculating a structure without the MD, and two accelerograms dangerous for a structure with the MD. This means that algorithmically in the first generation the frequency ω_1 should be used as the first main frequency, and in the second generation the first main frequency must be ω_2 .

For example, let us consider a bridge pier with two spans, for which the second span of the system acts as the MD due to its connection with the pier by an elastic-damping joint (Fig. 2). Such technical solutions are considered in the literature [7–9, 22]. The pier has dense sandy soils in the base with a deformation modulus $E_0 = 300 \text{ kg/cm}^2$ (30 MPa). The dynamic characteristics of the pier are given in Table 1. The MD under consideration is the MD of big mass and its optimum damping, i.e. inelastic resistant ratio γ , exceeds the critical value. The letter is difficult to achieve, therefore, in this example $\gamma = 0.5$ (25 % of critical value) is considered.

Table 1. Dynamic characteristics of the structure for which the calculated accelerogram is generated

Mode characteristics	Pier with one span			Pier with two spans with the second span used as the MD		
	The mode number			The mode number		
	1	2	3	1	2	3
Period, T, s	0.425	0.0433	0.0142	1.767	0.412	0.0433
Frequency, ω , s ⁻¹	14.80	145.03	441.8	3.556	15.246	145.03
Inelastic resistant ratio, γ	0.167	0.228	0.141	0.478	0.165	0.185

Table 2. Characteristics of generated inputs

Object to be calculated		Structure without the MD	Structure with the MD	
			Dominance on the first mode	Dominance on the second mode
Input characteristics	PGA, m/c ²	5.415	2.074	5.383
	I _A , m/c	2.874	0.303	3.911
	CAV, m/c	11.230	3.459	14.072
	SED, m ² /c	0.053	0.122	0.181
	κ	3.465	3.00	2.378

The results of calculating structures using generated accelerograms are shown in Figures 3–5 and in Table 3.

Table 3. Some results of structure calculations

Characteristics of structure calculations		Design accelerograms		
		For the structure without the MD	For the structure with the MD	
			At the first mode tuning	At the second mode tuning
displacements, m	The first span (structure top)	0.0587	0.011	0.0374
	The second span (MD)	-	0.001	0.0027
accelerations, m/s ²	The first span (structure top)	12.80	2.462	8.89
	The second span (MD)	-	0.123	0.534

Note, that the calculating the system with the MD using the accelerogram dangerous for the structure without the MD, gives an incorrect estimate of the MD efficiency. In this case, the maximum shift of the MD is 0.002 m, the maximum displacement of the structure is 0.027 m and the corresponding maximum accelerations are 0.385 m/s² and 6.605 m/s².

Conclusions

The abovementioned investigations made it possible to discover some peculiarities of seismic input setting for structures with tuned mass dampers. Among them one can stress the following

1) When generating seismic input in the form of a narrow-band process dangerous for a structure, several inputs corresponding to several resonant frequencies should be generated. In the example considered, the second natural frequency of the structure with the MD turned out to be dangerous.

2) It should also be stressed that when evaluating the effectiveness of the MD using accelerograms of earthquakes, the calculation of the structure without the MD and with the MD should be carried out using different accelerograms

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